

## In the Claims

1-3 (Cancelled)

4. (Currently amended) A portable device according to ~~claim 1~~ for providing continuous passive motion, the portable device comprising a brace and a drive mechanism, wherein :

- the portable device is adapted for providing continuous passive motion of a limb of a human or animal body having a torso, the limb comprising a distal end and a proximal end, the distal end being connected to the proximal end with a first joint, the proximal end being connected to the torso with a second joint,
- wherein the brace is adapted for supporting the distal end of the limb;
- wherein the drive mechanism is adapted for providing a settable continuous passive motion of the first joint and/or the second joint of the limb, said drive mechanism being coupled to said brace and controlling movement of the distal end of the limb;
- said passive motion is controlled in a first control point and a second control point on the distal end of the limb; and said drive mechanism comprises at least a first unit for controlling movement of said first control point on the distal end of the limb; and
- wherein said portable device furthermore comprises flexible positioning means for flexible positioning said brace and said drive mechanism on the body of a patient carrying said device, said positioning means being provided with a fastening means for fastening said brace and said drive mechanism to the body of a patient carrying said device in a stable position, whereby said drive mechanism is at least partially housed within said positioning means.

5-7. (Cancelled)

8. (Previously presented) A portable device according to claim 4, wherein said positioning means comprises an inflatable housing of flexible material provided with said fastening means, said housing allowing at least partial deformation when fastened on a body for providing a stable position.

9-11 (Cancelled)

12. ~~Currently amended~~) A portable device ~~according to claim 2~~ for providing continuous passive motion, the portable device comprising a brace and a drive mechanism, wherein :

- the portable device is adapted for providing continuous passive motion of a limb of a human or animal body having a torso, the limb comprising a distal end and a proximal end, the distal end being connected to the proximal end with a first joint, the proximal end being connected to the torso with a second joint,
- wherein the brace is adapted for supporting the distal end of the limb;
- wherein the drive mechanism is adapted for providing a settable continuous passive motion of the first joint and/or the second joint of the limb, said drive mechanism being coupled to said brace and controlling movement of the distal end of the limb;
- said passive motion is controlled in a first control point and a second control point on the distal end of the limb; and said drive mechanism comprises at least a first unit for controlling movement of said first control point on the distal end of the limb;
- wherein said drive mechanism further comprises a second unit for controlling the movement of said second control point of the distal end of the limb;
- wherein the first and second units of said drive mechanism consist of a triple spindle with electromotor with worm wheel transfer, being provided in a housing, allowing the units to induce a substantially vertical movement.

13. (cancelled)

14. (Previously presented) A portable device according to claim 4, wherein the positioning means further comprises a belt provided with fasteners, for positioning said device on a body.

15-18 (Cancelled)

19. ~~(Currently amended)~~ A portable device ~~according to claim 1~~ wherein for providing continuous passive motion, the portable device comprising a brace and a drive mechanism, wherein :

- the portable device is adapted for providing continuous passive motion of a limb of a human or animal body having a torso, the limb comprising a distal end and a proximal end, the distal end being connected to the proximal end with a first joint, the proximal end being connected to the torso with a second joint,
- wherein the brace is adapted for supporting the distal end of the limb;
- wherein the drive mechanism is adapted for providing a settable continuous passive motion of the first joint and/or the second joint of the limb, said drive mechanism being coupled to said brace and controlling movement of the distal end of the limb;
- said passive motion is controlled in a first control point and a second control point on the distal end of the limb; and said drive mechanism comprises at least a first unit for controlling movement of said first control point on the distal end of the limb;
- said portable device furthermore comprises a flexible positioner provided with a fastener, the flexible positioner being suitable for positioning said brace and said drive mechanism on the body of a patient carrying said device in a stable position, whereby said drive mechanism is at least partially housed within said positioner.

20. (previously presented) A portable device according to claim 19, wherein said positioner comprises an inflatable housing of flexible material provided with a fastener, said housing allowing at least partial deformation when fastened on a body for providing a stable position.

21. (previously presented) A portable device according to claim 19, wherein the positioner further comprises belts provided with fasteners, for positioning said device on a body.

22. (currently amended) A portable device according to claim [[1]]4, wherein the limb is an arm, the brace is adapted for supporting the distal end of the arm.

23. (New) A portable device according to claim 12, wherein the limb is an arm, the brace is adapted for supporting the distal end of the arm.

24. (New) A portable device according to claim 19, wherein the limb is an arm, the brace is adapted for supporting the distal end of the arm.